

San Diego State University

High-Speed Sports Camera Drone (Falcon)

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INTRODUCTION

- Research Question: How can we design and build a drone that can keep up with high-speed motorsport vehicles, such as Formula 1 cars, while delivering stable and immersive footage?
- **Background:** Traditional camera systems often fail to follow the speed and agility of modern race cars. As drone and camera technology evolve, there's a need for specialized aerial systems in sports broadcasting.
- Why It Matters: Viewers expect dynamic, real-time footage that matches the thrill of the race. Our drone aims to deliver that experience.
- **Context:** Inspired by innovations like the Red Bull FPV Drone, our project contributes to ongoing research in autonomous tracking, lightweight design, and flight stabilization.
- Visual Approach: We incorporate CAD designs, component diagrams, and track test results to illustrate how our drone accomplishes the task.

METHODS

- **Preliminary layout** Quadcopter, 5 in X-frame with four arms.
- **Component selection** Carbon-fiber frame, radio receiver, flight controller, power-distribution board, ESCs, brushless motors, Li-Po battery, HD camera, video transmitter, 3-Dprinted canopy & propellers.
- Fabrication & assembly 3-D-print canopy/props; mount hardware; solder all electronic boards and wiring.
- **PID tuning** Adjust P, I, D gains to maximize responsiveness and stability.
- **Test procedure** Fly the drone on a makeshift Formula 1 course; record top speed, lap times, and stability; log battery endurance.
- **Iterative cycle** Analyze test data \rightarrow revise propeller layout or canopy design \rightarrow re-test until objectives are met.

RESULTS/DISCUSSION

- **Performance goal** Minimum top speed \geq 120 mph with high stability.
- **Agility requirement** Must follow rapid turns and accelerations typical of Formula 1 tracks.
- **Expected footage quality** Fixed wide-lens camera streams clear video at racing speeds.
- **Key design choice** 3-D-printed canopy/props to cut drag while keeping weight low.
- Next milestone Complete first full-speed test and compare lap times to earlier configurations.

Top Speed Comparison of Fastest FPV Drones



3D CAD Design





CONCLUSIONS

- Proposed build—test—iterate plan positions the team to achieve
- 175-mph speed target while maintaining video stability. 3-D-printed aerodynamic components and careful PID tuning are critical to meeting both speed and agility requirements.
- Future work: add autonomous vehicle-tracking (YOLO/OpenCV) and extend flight time for longer motorsport coverage.

REFERENCES

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